Followed tip at the end of <https://dronekit-python.readthedocs.io/en/latest/develop/sitl_setup.html#viewing-uav-on-map>

Example script example.py contains mission downloaded from dronekit-SITL

Open mission planner

Run example.py (default SITL TCP port 5760)

Connect Mission Planner to TCP 127.0.0.1:5763 to watch mission

Fixed example file with linter as circle.py